

Improved torque sensitivity and normal force resolution for routine measurements

Dr. Annette Fischer, Thermo Fisher Scientific, Process Instruments, Karlsruhe, Germany

HAAKE RheoStress 6000

The new HAAKE RheoStress 6000 benefits from the latest MARS technology developments. The improved specifications are regarding two components, improved air bearing specifications and the change of the normal force sensor technology.

The normal force sensor of the HAAKE RheoStress 6000 is based on temperature-compensated strain gauge technology and enables normal force measurements in the range of 0.01 to 50 N in both positive and negative direction. This technology offers the possibility to perform sensitive normal force measurements even on samples with low visco-elasticity.

In addition the new sensor enables to control the normal force in the sample to compensate for sample shrinkage and expansion when measuring semisolids.

The patented 4th generation air bearing in the HAAKE RheoStress 6000 is the result of more than 25 years of experience with the design and manufacturing of porous carbon air bearings. The air bearing consists of three individual air bearings: One axial air bearing that supports the motor shaft in the vertical (axial) direction and is responsible for excellent axial stiffness. Two widely spaced radial air bearings that support the motor shaft in the radial direction and prevent the shaft from tilting.

Two widely spaced radial air bearings that support the motor shaft in the radial direction and prevent the shaft from tilting.

Viscosity curve

CS (Controlled stress) – Mode

Our latest advances in air-bearing technology plus accurate residual torque correction (MSC = Micro Stress Control), enable measurements down to 0.2 μNm .

Figure 1 shows the result of an experiment in which the shear stress was stepwise increased. Even at a torque value of 0.05 μNm (clearly

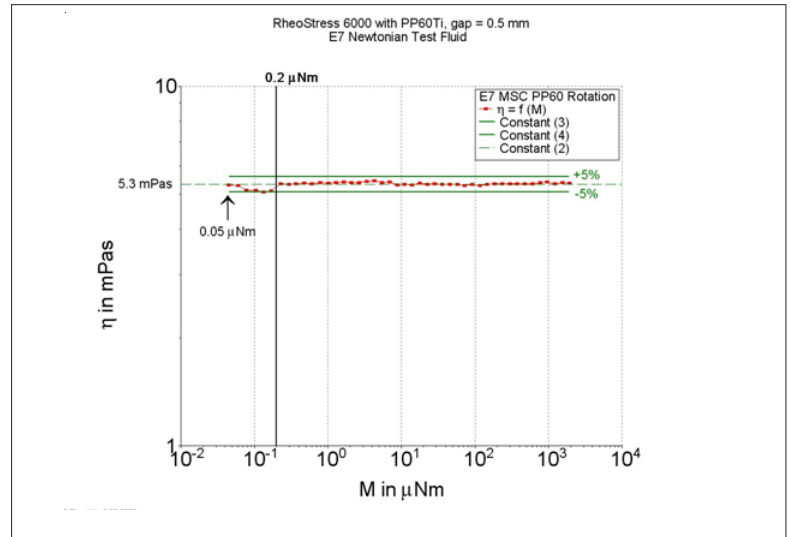


Figure 1: Viscosity curve of a 5.3 mPas oil at 20 °C

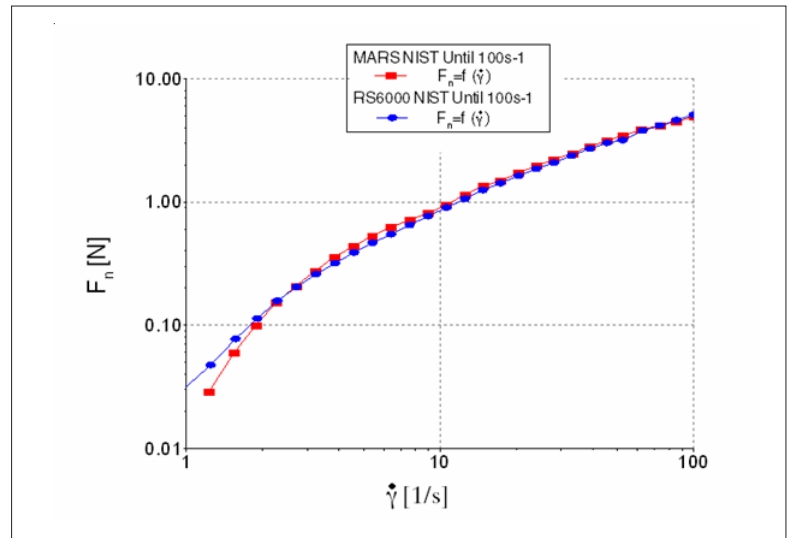


Figure 2: Normal force measurements of the standard reference material NIST 2490

below the specified lowest torque) the measured viscosity is still within $\pm 5\%$ from the specified value.

Normal Force measurement

The HAAKE RheoStress 6000 is equipped with a new normal force sensor based on robust and very sensitive strain gauges with integrated temperature compensation and a measuring range from 0.01 N to 50 N in positive and negative directions.

The curves in figure 2 show a very good correspondence between the normal force measurement with the HAAKE MARS and the normal force measurement with the HAAKE RheoStress 6000. The tests were performed at $T=20\text{ }^\circ\text{C}$, CR-rot steps, Waiting 10 s, integration 3 s, log scale.

In a rotational measurement the centrifugal forces acting on the sample will result in a negative normal force F_{nc} on the rotating cone given by

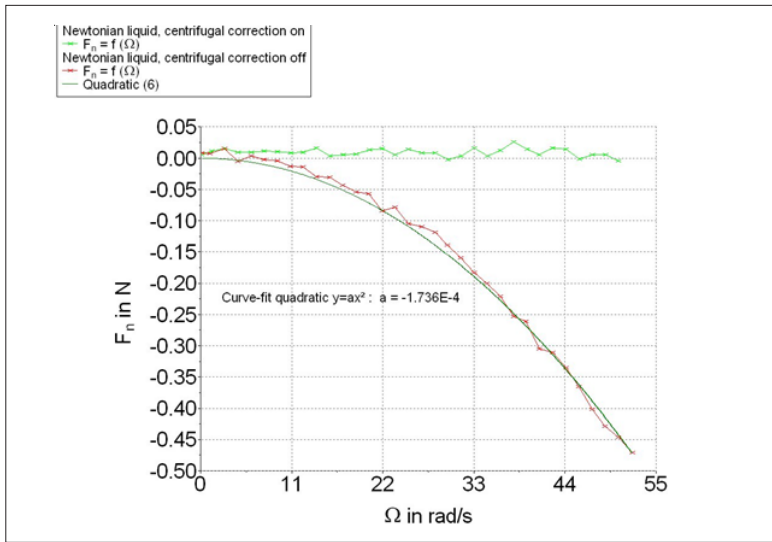


Figure 3: Normal force measurements of an oil at 20 °C

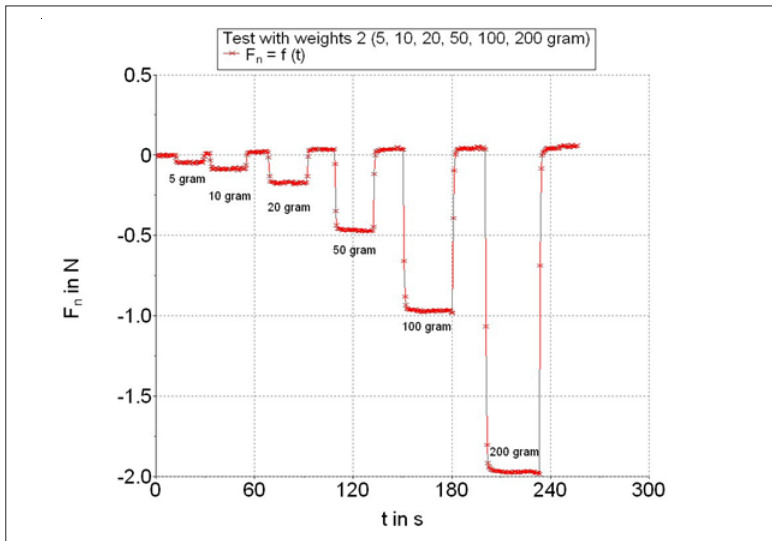


Figure 4: Normal force measurements after placing different weights on the rotor plate

equation [1] in which ρ is the density of the sample, Ω the angular velocity and R the radius of the cone.

$$F_{nc} = \frac{-3\pi\rho R^4}{40}\Omega^2 \quad [1]$$

This effect can be used to demonstrate that the normal force sensor is working correctly by measuring a Newtonian fluid (for which the first normal stress coefficient $N_1 = 0$) with the centrifugal force correction in the software disabled (by setting the density to zero).

The measured data should then correspond with equation [1]. Figure 3 shows that this is the case: with the density of the sample $\rho = 901 \text{ kg/m}^3$ and the radius of the plate

$R = 0.03 \text{ m}$ equation [1] becomes $F_{nc} = -1.72 \cdot 10^{-4} \Omega^2$, this corresponds nicely with the parameter $a = -1.736 \cdot 10^{-4}$ from the quadratic curve fit in figure 3.

With the centrifugal correction in the software enabled the measured normal force signal $F_n - F_{nc}$ should be zero, figure 3 shows that this is the case.

Figure 4 shows the measured normal force after consecutively applying weights of 5, 10, 20, 50, 100 and 200 g to the motor shaft. Applying a weight of 200 g correctly results in a measured normal force of $F = m \cdot g = 0.2 \cdot 9.81 = 1.962 \text{ N}$.

**Thermo Fisher Scientific
Process Instruments**

International/Germany
Dieselstr. 4,
76227 Karlsruhe
Tel. +49(0)721 40 94-444
info.mc.de@thermofisher.com

Benelux
Tel. +31 (0) 76 5 87 98 88
info.mc.nl@thermofisher.com

China
Tel. +86 (21) 68 65 45 88
info.china@thermofisher.com

France
Tel. +33 (0) 1 60 92 48 00
info.mc.fr@thermofisher.com

India
Tel. +91 (22) 27 78 11 01
info.mc.in@thermofisher.com

United Kingdom
Tel. +44 (0) 1785 81 36 48
info.mc.uk@thermofisher.com

USA
Tel. 603 436 9444
info.mc.us@thermofisher.com

www.thermo.com/mc

V231_21.11.07

© 2007/11 Thermo Fisher Scientific · All rights reserved · This document is for informational purposes only and is subject to change without notice.